# ECEN 615 Methods of Electric Power Systems Analysis

**Lecture 17: Sensitivity Methods** 

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#### **Announcements**



- Read Chapter 7 from the book (the term reliability is now used instead of security)
- Homework 4 is due on Thursday October 31.



Denote the system state by

$$\mathbf{x} \triangleq \begin{bmatrix} \mathbf{\theta} \\ \mathbf{V} \end{bmatrix} \qquad \mathbf{\theta} \triangleq [\boldsymbol{\theta}^{1}, \boldsymbol{\theta}^{2}, \cdots, \boldsymbol{\theta}^{N}]^{T} \\ \mathbf{V} \triangleq [\boldsymbol{V}^{1}, \boldsymbol{V}^{2}, \cdots, \boldsymbol{V}^{N}]^{T}$$

• Denote the conditions corresponding to the existing commitment/dispatch by  $\mathbf{s}^{(0)}$ ,  $\mathbf{p}^{(0)}$  and  $\mathbf{f}^{(0)}$  so that

$$\begin{cases} \mathbf{g}(\mathbf{x}^{(\theta)}, \mathbf{p}^{(\theta)}) = \mathbf{0} & \text{the power flow equations} \\ \mathbf{f}^{(\theta)} = \mathbf{h}(\mathbf{x}^{(\theta)}) & \text{line real power flow vector} \end{cases}$$



$$\mathbf{g}(\mathbf{x},\mathbf{p}) = \begin{bmatrix} \mathbf{g}^{P}(\mathbf{x},\mathbf{p}) \\ \mathbf{g}^{Q}(\mathbf{x},\mathbf{p}) \end{bmatrix}$$

**g** includes the real and reactive power balance equations

$$g_k^P(\underline{s},\underline{p}) = V^k \sum_{m=1}^N \left( V^m \left[ G_{km} cos(\theta^k - \theta^m) + B_{km} sin(\theta^k - \theta^m) \right] \right) - p^k$$

$$g_{k}^{Q}(\underline{s},\underline{p}) = V^{m} \sum_{m=1}^{N} \left( V^{m} \left[ G_{km} sin(\theta^{k} - \theta^{m}) - B_{km} cos(\theta^{k} - \theta^{m}) \right] \right) - q^{k}$$

$$h_{\ell}(\underline{s}) = g_{\ell}\left[\left(V^{i}\right)^{2} - V^{i}V^{j}cos(\theta^{i} - \theta^{j})\right] - b_{\ell}V^{i}V^{j}sin(\theta^{i} - \theta^{j}), \ \ell = (i,j)$$



• For a small change,  $\Delta \mathbf{p}$ , that moves the injection from  $\mathbf{p}^{(0)}$  to  $\mathbf{p}^{(0)} + \Delta \mathbf{p}$ , we have a corresponding change in the state  $\Delta \mathbf{x}$  with

$$\mathbf{g}\left(\mathbf{x}^{(\theta)} + \Delta\mathbf{x}, \boldsymbol{p}^{(\theta)} + \Delta\mathbf{p}\right) = \mathbf{0}$$

• We then apply a first order Taylor's series expansion

$$g\left(\mathbf{x}^{(\theta)} + \Delta\mathbf{x}, \mathbf{p}^{(\theta)} + \Delta\mathbf{p}\right) = g\left(\mathbf{x}^{(\theta)}, \mathbf{p}^{(\theta)}\right) + \frac{\partial g}{\partial \mathbf{x}}\bigg|_{\left(\mathbf{x}^{(\theta)}, \mathbf{p}^{(\theta)}\right)} \Delta\mathbf{x}$$

$$+ \frac{\partial \mathbf{g}}{\partial \mathbf{p}}\bigg|_{\left(\mathbf{x}^{(\theta)}\mathbf{p}^{(\theta)}\right)} \Delta p + h.o.t.$$



- We consider this to be a "small signal" change, so we can neglect the higher order terms (h.o.t.) in the expansion
- Hence we should still be satisfying the power balance equations with this perturbation; so

$$\left. \frac{\partial \mathbf{g}}{\partial \mathbf{x}} \right|_{\left(\mathbf{x}^{(\theta)}\mathbf{p}^{(\theta)}\right)} \Delta \mathbf{x} + \left. \frac{\partial \mathbf{g}}{\partial \mathbf{p}} \right|_{\left(\mathbf{x}^{(\theta)}\mathbf{p}^{(\theta)}\right)} \Delta \mathbf{p} \approx \mathbf{0}$$



Also, from the power flow equations, we obtain

$$\frac{\partial \mathbf{g}}{\partial \mathbf{p}} = \begin{bmatrix} \frac{\partial \mathbf{g}^{P}}{\partial \mathbf{p}} \\ \frac{\partial \mathbf{g}^{Q}}{\partial \mathbf{p}} \end{bmatrix} = \begin{bmatrix} -\mathbf{I} \\ \mathbf{0} \end{bmatrix}$$

and then just the power flow Jacobian

$$\frac{\partial \mathbf{g}}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial \mathbf{g}^{P}}{\partial \mathbf{\theta}} & \frac{\partial \mathbf{g}^{P}}{\partial \mathbf{V}} \\ \frac{\partial \mathbf{g}^{Q}}{\partial \mathbf{\theta}} & \frac{\partial \mathbf{g}^{Q}}{\partial \mathbf{V}} \end{bmatrix} = \mathbf{J}(\mathbf{x}, \mathbf{p})$$



 With the standard assumption that the power flow Jacobian is nonsingular, then

$$\Delta \mathbf{x} \approx \left[ \mathbf{J}(\mathbf{x}^{(0)}, \mathbf{p}^{(0)}) \right]^{-1} \begin{bmatrix} \mathbf{I} \\ \mathbf{0} \end{bmatrix} \Delta \mathbf{p}$$

 We can then compute the change in the line real power flow vector

$$\Delta \mathbf{f} \approx \left[\frac{\partial \mathbf{h}}{\partial \mathbf{x}}\right]^T \Delta \mathbf{s} \approx \left[\frac{\partial \mathbf{h}}{\partial \mathbf{x}}\right]^T \left[J(\mathbf{x}^{(\theta)}, \mathbf{p}^{(\theta)})\right]^{-1} \left[\mathbf{I} \atop \mathbf{0}\right] \Delta \mathbf{p}$$

# **Sensitivity Comments**



- Sensitivities can easily be calculated even for large systems
  - If  $\Delta \mathbf{p}$  is sparse (just a few injections) then we can use a fast forward; if sensitivities on a subset of lines are desired we could also use a fast backward
- Sensitivities are dependent upon the operating point
  - They also include the impact of marginal losses
- Sensitivities could easily be expanded to include additional variables in **x** (such as phase shifter angle), or additional equations, such as reactive power flow

# Sensitivity Comments, cont.



- Sensitivities are used in the optimal power flow; in that context a common application is to determine the sensitivities of an overloaded line to injections at all the buses
- In the below equation, how could we quickly get these values?

$$\Delta \mathbf{f} \approx \left[\frac{\partial \mathbf{h}}{\partial \mathbf{x}}\right]^T \Delta f \approx \left[\frac{\partial \mathbf{h}}{\partial x}\right]^T \left[J(\mathbf{x}^{(\theta)}, \mathbf{p}^{(\theta)})\right]^{-1} \left[\begin{matrix} \mathbf{I} \\ \mathbf{0} \end{matrix}\right] \Delta \mathbf{p}$$

A useful reference is O. Alsac, J. Bright, M. Prais, B. Stott,
 "Further Developments in LP-Based Optimal Power Flow,"
 IEEE. Trans. on Power Systems, August 1990, pp. 697-711;
 especially see equation 3.

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# Sensitivity Example in PowerWorld



- Open case B5\_DistFact and then Select Tools,
   Sensitivities, Flow and Voltage Sensitivities
  - Select Single Meter, Multiple Transfers, Buses page
  - Select the Device Type (Line/XFMR), Flow Type (MW),
     then select the line (from Bus 2 to Bus 3)
  - Click Calculate Sensitivities; this shows impact of a single injection going to the slack bus (Bus 1)
  - For our example of a transfer from 2 to 3 the value is the result we get for bus 2 (0.5440) minus the result for bus 3 (-0.1808) = 0.7248
  - With a flow of 118 MW, we would hit the 150 MW limit with (150-118)/0.7248 =44.1MW, close to the limit we found of 45MW

# Sensitivity Example in PowerWorld



- If we change the conditions to the anticipated maximum loading (changing the load at 2 from 118 to 118+44=162 MW) and we re-evaluate the sensitivity we note it has changed little (from -0.7248 to -0.7241)
  - Hence a linear approximation (at least for this scenario) could be justified
- With what we know so far, to handle the contingency situation, we would have to simulate the contingency, and reevaluate the sensitivity values
  - We'll be developing a quicker (but more approximate)
     approach next

# **Linearized Sensitivity Analysis**



- By using the approximations from the fast decoupled power flow we can get sensitivity values that are independent of the current state. That is, by using the B' and B'' matrices
- For line flow we can approximate

$$h_{\ell}(\underline{s}) = g_{\ell}\left[\left(V^{i}\right)^{2} - V^{i}V^{j}cos(\theta^{i} - \theta^{j})\right] - b_{\ell}V^{i}V^{j}sin(\theta^{i} - \theta^{j}), \ \ell = (i,j)$$

By using the FDPF appxomations

$$h_{\ell}(\underline{s}) \approx -b_{\ell}(\theta^{i} - \theta^{j}) = \frac{(\theta^{i} - \theta^{j})}{X_{\ell}}, \ \ell = (i, j)$$

# **Linearized Sensitivity Analysis**



• Also, for each line  $\ell$ 

$$\frac{\partial h_{\ell}}{\partial \theta} \approx -b_{\ell} \mathbf{a}_{\ell} \qquad \frac{\partial h_{\ell}}{\partial \mathbf{V}} \approx \mathbf{0}$$
and so,

$$\frac{\partial \mathbf{h}}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial \mathbf{h}}{\partial \mathbf{\theta}} \\ \frac{\partial \mathbf{h}}{\partial \mathbf{V}} \end{bmatrix} = -\begin{bmatrix} \mathbf{b}_{\ell_1} \mathbf{a}_1 & \cdots & \mathbf{b}_{\ell_L} \mathbf{a}_L \\ \vdots & \ddots & \vdots \\ \mathbf{0} \end{bmatrix} \approx \begin{bmatrix} \mathbf{A}^T \tilde{\mathbf{B}} \\ \mathbf{0} \end{bmatrix}$$

# **Sensitivity Analysis: Recall the Matrix Notation**



• The series admittance of line  $\ell$  is  $g_{\ell} + jb_{\ell}$  and we define  $\tilde{\mathbf{B}} \triangleq -diag\{b_1,b_2,\cdots,b_L\}$ 

$$\mathbf{A} \triangleq \begin{bmatrix} \mathbf{a}_{1}^{T} \\ \mathbf{a}_{2}^{T} \\ \vdots \\ \mathbf{a}_{L}^{T} \end{bmatrix}$$

where the component j of  $\mathbf{a}_i$  is nonzero whenever line  $\ell_i$  is coincident with node j. Hence  $\mathbf{A}$  is quite sparse, with at most two nonzeros per row

#### **Linearized Active Power Flow Model**



• Under these assumptions the change in the real power line flows are given as

$$\Delta \mathbf{f} \approx \begin{bmatrix} \tilde{\mathbf{B}} \mathbf{A} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{B'} & \mathbf{0} \\ \mathbf{0} & \mathbf{B''} \end{bmatrix}^{-1} \begin{bmatrix} \mathbf{I} \\ \mathbf{0} \end{bmatrix} \Delta \mathbf{p} = \underbrace{\tilde{\mathbf{B}} \mathbf{A} \begin{bmatrix} \mathbf{B'} \end{bmatrix}^{-1} \Delta \mathbf{p}}_{-1} = \Psi \Delta \mathbf{p}$$

• The constant matrix  $\Psi \triangleq \tilde{\mathbf{B}}\mathbf{A}[\mathbf{B'}]^{-1}$  is called the injection shift factor matrix (ISF)

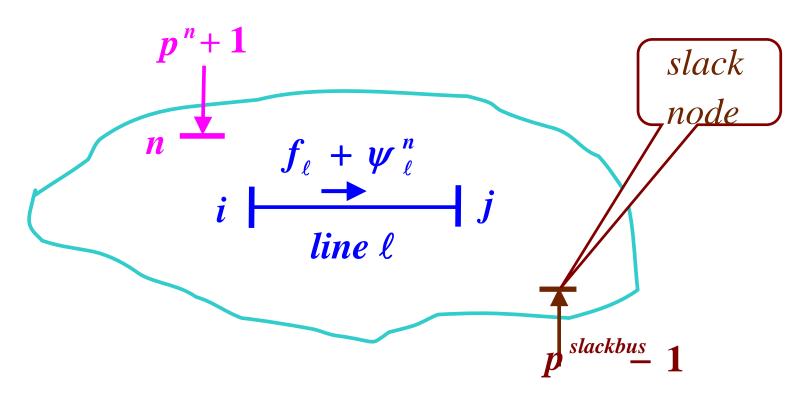
# Injection Shift Factors (ISFs)



- The element  $\psi_{\ell}^n$  in row  $\ell$  and column n of  $\Psi$  is called the injection shift factor (*ISF*) of line  $\ell$  with respect to the injection at node n
  - Absorbed at the slack bus, so it is slack bus dependent
- Terms generation shift factor (GSF) and load shift factor (LSF) are also used (such as by NERC)
  - Same concept, just a variation in the sign whether it is a generator or a load
  - Sometimes the associated element is not a single line, but rather a combination of lines (an interface)
- Terms used in North America are defined in the NERC glossary (http://www.nerc.com/files/glossary\_of\_terms.pdf)

# **ISF** Interpretation





 $\psi_{\ell}^{n}$  is the fraction of the additional 1 *MW* injection at node *n* that goes though line  $\ell$ 

# **ISF Properties**



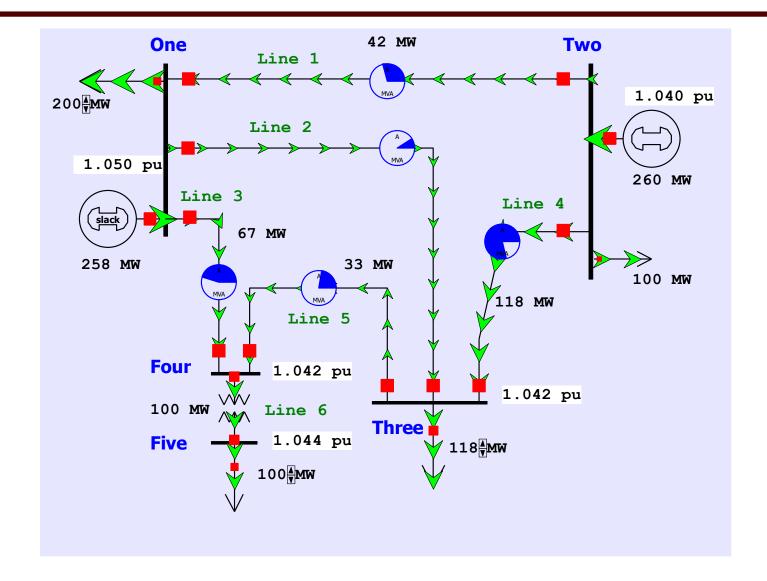
- By definition,  $\psi_{\ell}^{n}$  depends on the location of the slack bus
- By definition,  $\psi_{\ell}^{slackbus} \equiv 0$  for  $\forall \ell \in L$  since the injection and withdrawal buses are identical in this case and, consequently, no flow arises on any line  $\ell$
- The magnitude of  $\psi_{\ell}^{n}$  is at most 1 since

$$-1 \leq \psi^n \leq 1$$

Note, this is strictly true only for the linear (lossless) case. In the nonlinear case, it is possible that a transaction decreases losses. Hence a 1 MW injection could change a line flow by more than 1 MW.

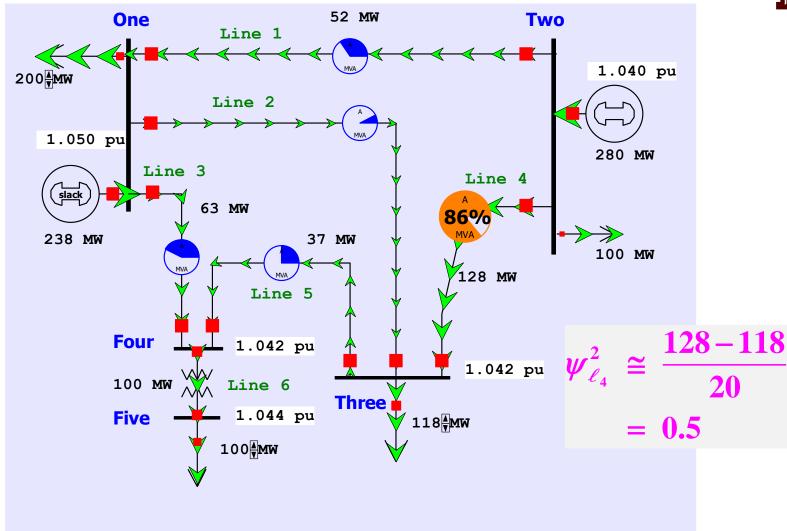
# Five Bus Example Reference





# Five Bus ISF, Line 4, Bus 2 (to Slack)

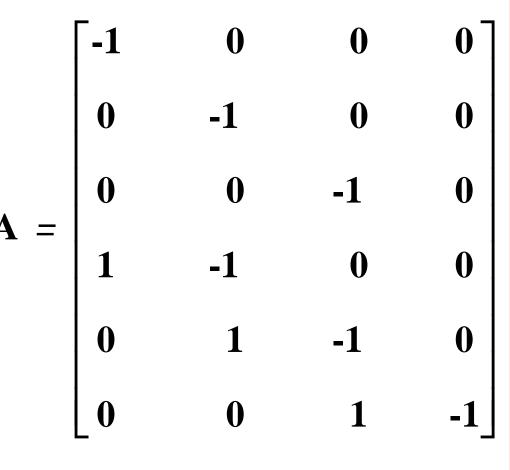




# Five Bus Example



$$\tilde{\mathbf{B}} = -diag\{6.25, 12.5, 12.5, 12.5, 12.5, 10\}$$



The row of **A** correspond to the lines and transformers, the columns correspond to the non-slack buses (buses 2 to 5); for each line there is a 1 at one end, a -1 at the other end (hence an assumed sign convention!). Here we put a 1 for the lower numbered bus, so positive flow is assumed from the lower numbered bus to the higher number

# Five Bus Example



$$\mathbf{B'} = \mathbf{A}^T \tilde{\mathbf{B}} \mathbf{A} = \begin{bmatrix} -18.75 & 12.5 & 0 & 0 \\ 12.5 & -37.5 & 12.5 & 0 \\ 0 & 12.5 & -35 & 10 \\ 0 & 0 & 10 & -10 \end{bmatrix}$$

$$\underline{\Psi} = \underline{\tilde{B}} \underline{A} [\underline{B}']^{-1} = \begin{bmatrix} -0.4545 & -0.1818 & -0.0909 & -0.0909 \\ -0.3636 & -0.5455 & -0.2727 & -0.2727 \\ -0.1818 & -0.2727 & -0.6364 & -0.6364 \\ \hline 0.5455 & -0.1818 & -0.0909 & -0.0909 \\ \hline 0.1818 & 0.2727 & -0.3636 & -0.3636 \\ \hline 0 & 0 & 0 & -1.0000 \end{bmatrix}$$

With bus 1 as the slack, the buses (columns) go for 2 to 5

# **Five Bus Example Comments**



- At first glance the numerically determined value of (128-118)/20=0.5 does not match closely with the analytic value of 0.5455; however, in doing the subtraction we are losing numeric accuracy
  - Adding more digits helps (128.40 117.55)/20 = 0.5425
- The previous matrix derivation isn't intended for actual computation;  $\Psi$  is a full matrix so we would seldom compute all of its values
- Sparse vector methods can be used if we are only interested in the ISFs for certain lines and certain buses

#### **Distribution Factors**

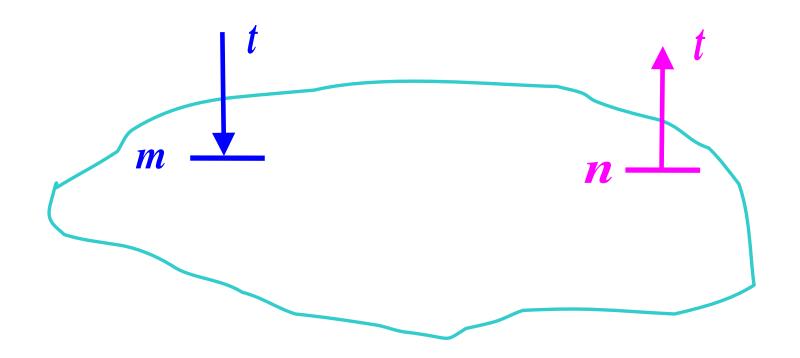


- Various additional distribution factors may be defined
  - power transfer distribution factor (PTDF)
  - line outage distribution factor (LODF)
  - line addition distribution factor (LADF)
  - outage transfer distribution factor (OTDF)
- These factors may be derived from the ISFs making judicious use of the superposition principle

#### **Definition: Basic Transaction**



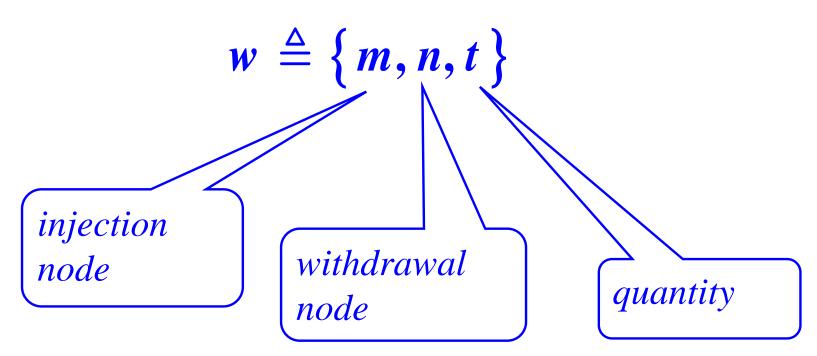
 A basic transaction involves the transfer of a specified amount of power t from an injection node m to a withdrawal node n



#### **Definition: Basic Transaction**



• We use the notation



to denote a basic transaction

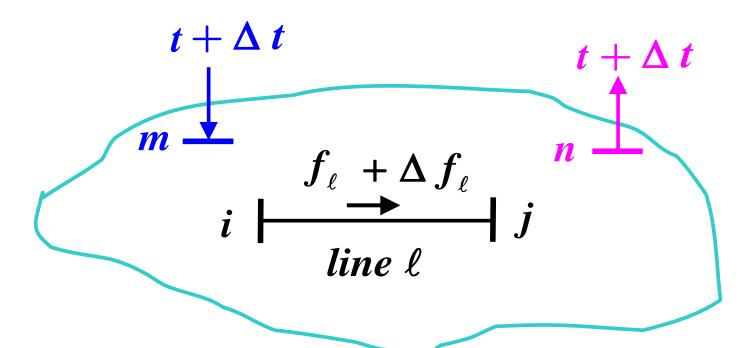
#### **Definition: PTDF**



- NERC defines a PTDF as
  - "In the pre-contingency configuration of a system under study, a measure of the responsiveness or change in electrical loadings on transmission system Facilities due to a change in electric power transfer from one area to another, expressed in percent (up to 100%) of the change in power transfer"
  - Transaction dependent
- We'll use the notation  $\varphi_{\ell}^{(w)}$  to indicate the PTDF on line  $\ell$  with respect to basic transaction w
- In the lossless formulation presented here (and commonly used) it is slack bus independent

#### **PTDFs**

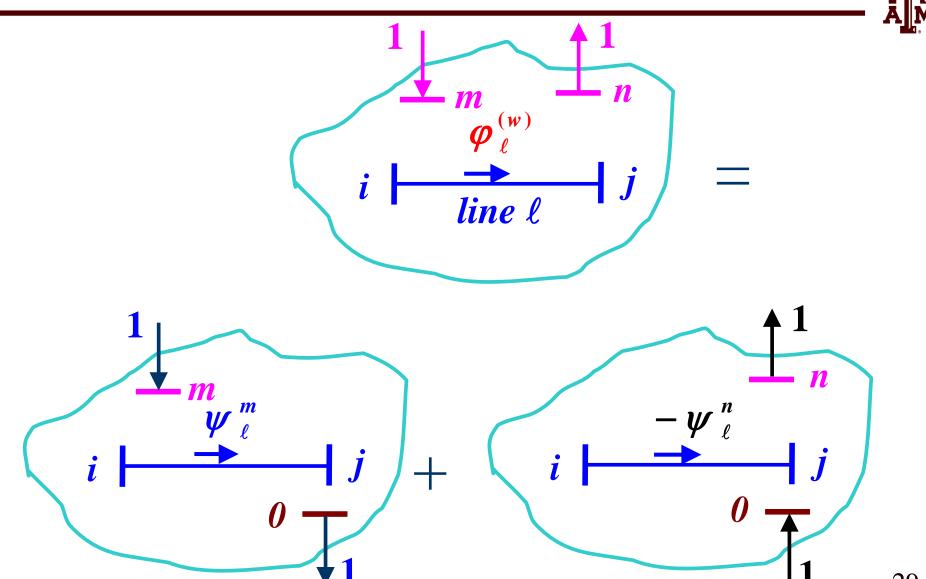




$$\varphi_{\ell}^{(w)} \triangleq \frac{\Delta f_{\ell}}{\Delta t}$$

Note, the PTDF is independent of the amount t; which is often expressed as a percent

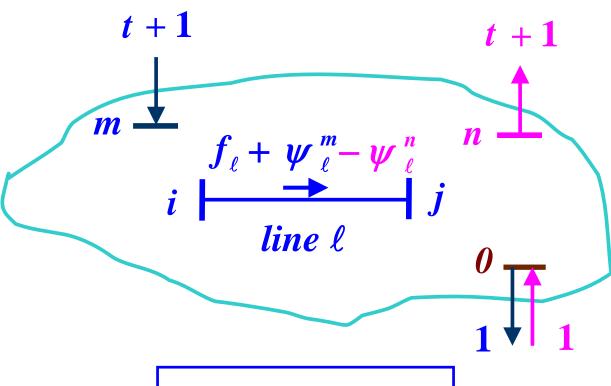
#### **PTDF Evaluation in Two Parts**





#### **PTDF Evaluation**



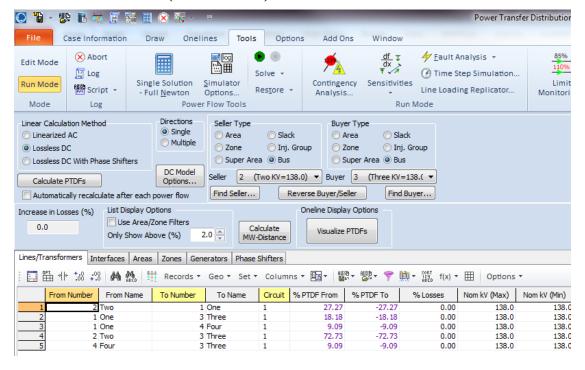


$$\varphi_{\ell}^{(w)} = \psi_{\ell}^{m} - \psi_{\ell}^{n}$$

# Calculating PTDFs in PowerWorld



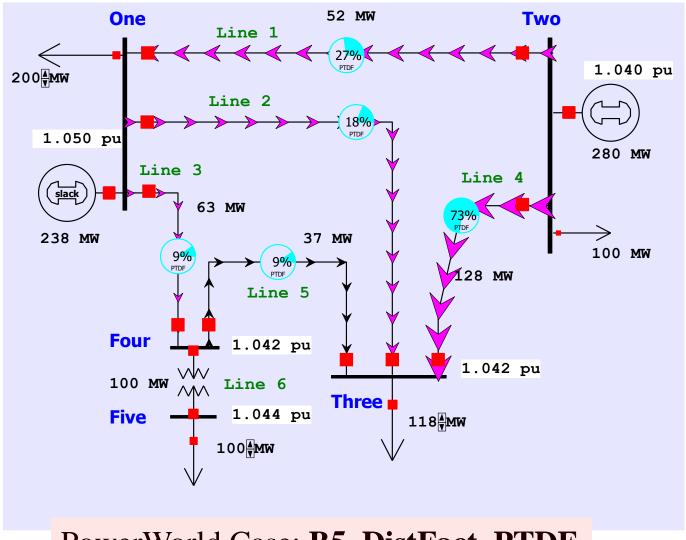
- PowerWorld provides a number of options for calculating and visualizing PTDFs
  - Select Tools, Sensitivities, Power Transfer Distribution Factors (PTDFs)



Results are shown for the five bus case for the Bus 2 to Bus 3 transaction

#### **Five Bus PTDF Visualization**

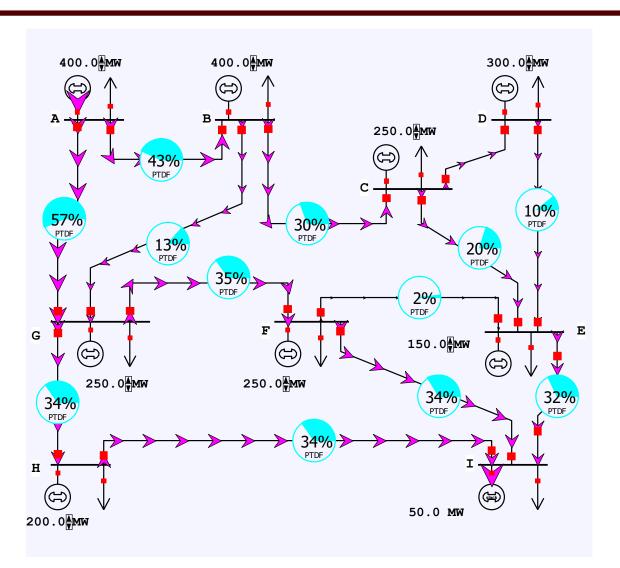




PowerWorld Case: B5\_DistFact\_PTDF

# Nine Bus PTDF Example



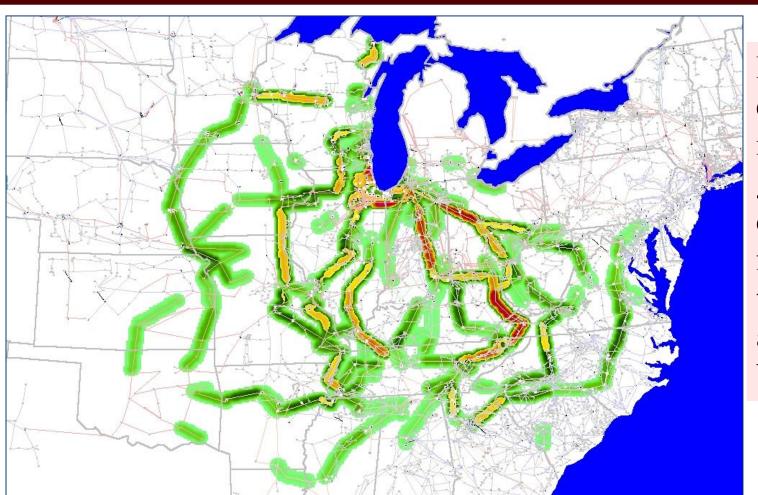


Display shows the PTDFs for a basic transaction from Bus A to Bus I. Note that 100% of the transaction leaves Bus A and 100% arrives at Bus I

PowerWorld Case: **B9\_PTDF** 

# **Eastern Interconnect Example: Wisconsin Utility to TVA PTDFs**





In this example multiple generators contribute for both the seller and the buyer

Contours show lines that would carry at least 2% of a power transfer from Wisconsin to TVA

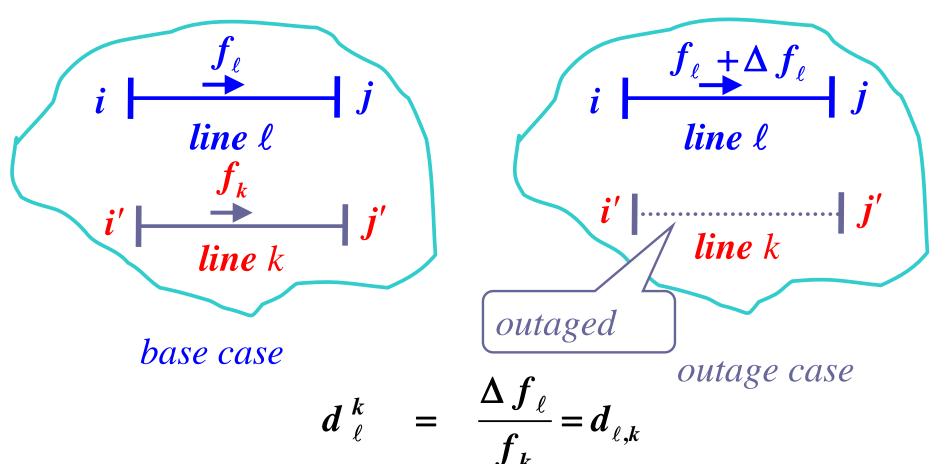
# Line Outage Distribution Factors (LODFs)



- Power system operation is practically always limited by contingencies, with line outages comprising a large number of the contingencies
- Desire is to determine the impact of a line outage (either a transmission line or a transformer) on other system real power flows without having to explicitly solve the power flow for the contingency
- These values are provided by the LODFs
- The LODF  $d_{\ell}^{k}$  is the portion of the pre-outage real power line flow on line k that is redistributed to line  $\ell$  as a result of the outage of line k

#### **LODFs**



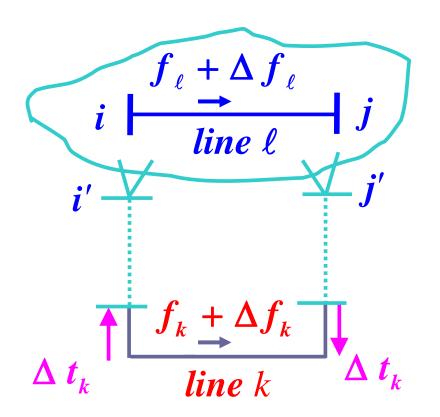


Best reference is Chapter 7 of the course book

#### **LODF** Evaluation



We simulate the impact of the outage of line k by adding the basic transaction  $w_k = \{i', j', \Delta t_k\}$ 



and selecting  $\Delta t_k$  in such a way that the flows on the dashed lines become exactly zero

In general this  $\Delta t_k$  is not equal to the original line flow

#### **LODF** Evaluation



• We select  $\Delta t_k$  to be such that

$$f_k + \Delta f_k - \Delta t_k = 0$$

where  $\Delta f_k$  is the active power flow change on the line k due to the transaction  $w_k$ 

• The line k flow from w<sub>k</sub> depends on its PTDF

$$\Delta f_k = \varphi_k^{(w_k)} \Delta t_k$$

it follows that 
$$\Delta t_k = \frac{f_k}{1 - \varphi_k^{(w_k)}} = \frac{f_k}{1 - (\psi_k^{i'} - \psi_k^{j'})}$$

#### **LODF** Evaluation



• For the rest of the network, the impacts of the outage of line k are the same as the impacts of the additional basic transaction  $w_k$ 

$$\Rightarrow \Delta f_{\ell} = \varphi_{\ell}^{(w_k)} \Delta t_k = \frac{\varphi_{\ell}^{(w_k)}}{1 - \varphi_k^{(w_k)}} f_k$$

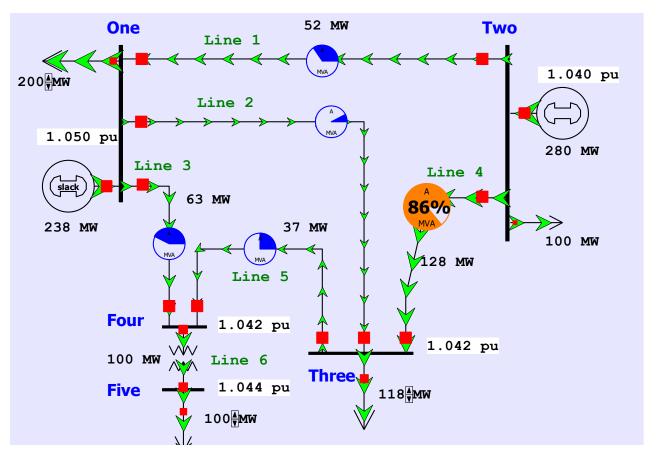
• Therefore, by definition the LODF is

$$d_{\ell}^{k} = \frac{\Delta f_{\ell}}{f_{k}} = \frac{\varphi_{\ell}^{(w_{k})}}{1 - \varphi_{k}^{(w_{k})}}$$

# Five Bus Example



• Assume we wish to calculate the values for the outage of line 4 (between buses 2 and 3); this is line k



Say we wish to know the change in flow on the line 3 (Buses 3 to 4). PTDFs for a transaction from 2 to 3 are 0.7273 on line 4 and 0.0909 on line 3

# Five Bus Example



Hence we get

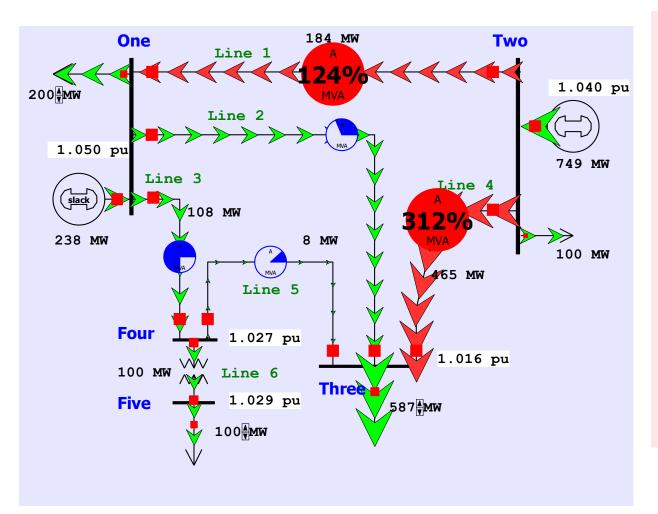
$$\Delta t_k = \frac{f_k}{1 - \varphi_k^{(w_k)}} = \frac{128}{1 - 0.7273} = 469.4$$

$$d_{3}^{4} = \frac{\Delta f_{3}}{f_{4}} = \frac{\varphi_{3}^{(w_{4})}}{1 - \varphi_{4}^{(w_{4})}} = \frac{0.0909}{1 - 0.7273} = 0.333$$

$$\Delta f_3 = (0.333) f_4 = 0.333 \times 128 = 42.66 \text{MW}$$

# Five Bus Example Compensated



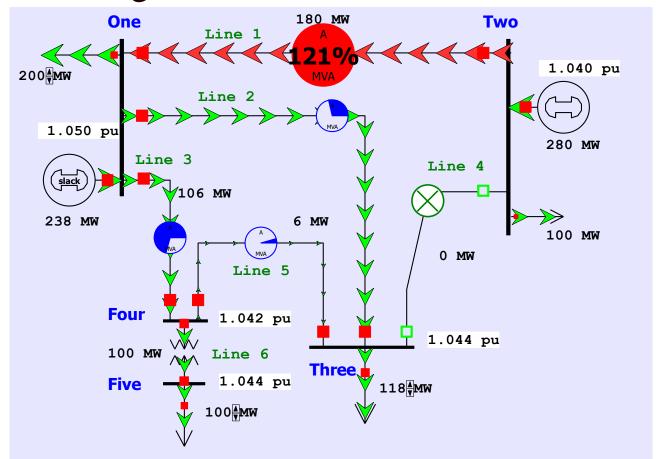


Here is the system with the compensation added to bus 2 and removed at bus 3; we are canceling the impact of the line 4 flow for the reset of the network.

### Five Bus Example



Below we see the network with the line actually outaged



The line 3 flow changed from 63 MW to 106 MW, an increase of 43 MW, matching the LODF value