#### ECEN 615 Methods of Electric Power Systems Analysis Lecture 11 Sensitivity

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#### Announcements



- Homework 3 should be done before the first exam but need not be turned in
- Start reading Chapter 7 (the term reliability is now often used instead of security)
- First exam is in class on Thursday Oct 1
  - Distance learning students do not need to take the exam during the class period
  - Closed book, notes. One 8.5 by 11 inch notesheet and calculators allowed
  - Last's years exam is available in Canvas with answers
  - Lecture 12 will be on the August 14, 2003 Blackout

# **Power Flow Topology Processing**



- Anytime a status change occurs the power flow must perform topology processing to determine whether there are either 1) new islands or 2) islands have merged
- Determination is needed to determine whether the island is "viable." That is, could it truly function as an independent system, or should the buses just be marked as dead
  - A quite common occurrence is when a single load or generator is isolated; in the case of a load it can be immediately killed; generators are more tricky

# **Topology Processing Algorithm**



- Since topology processing is performed often, it must be quick (order n ln(n))!
- Simple, yet quick topology processing algoritm
  - Set all buses as being in their own island (equal to bus number)
  - Set ChangeInIslandStatus true
  - While ChangeInIslandStatus Do
    - Go through all the in-service lines, setting the islands for each of the buses to be the smaller island number; if the island numbers are different set ChangeInIslandStatus true
  - Determine which islands are viable, assigning a slack bus as necessary

This algorithm does depend on the depth of the system

#### **Example of Island Formation**



Splitting large systems requires a careful consideration of the flow on the island tie-lines as they are opened

#### **Bus Branch versus Node Breaker**



• Due to a variety of issues during the 1970's and 1980's the real-time operations and planning stages of power systems adopted different modeling approaches

#### **Real-Time Operations**

Use detailed node/breaker model EMS system as a set of integrated applications and processes Real-time operating system Real-time databases

#### Planning

Use simplified bus/branch model PC approach Use of files Stand-alone applications

Entire data sets and software tools developed around these two distinct power system models

#### Google View of a 345 kV Substation





#### Example of Using a Disconnect to Break Load Current





# **Substation Configurations**



- Several different substation breaker/disconnect configurations are common:
- Single bus: simple but a fault any where requires taking out the entire substation; also doing breaker or disconnect maintenance requires taking out the associated line



Fig B: Single Bus

# Substation Configurations, cont.

- Main and Transfer Bus:
  Now the breakers can be taken out for maintenance without taking out a line, but protection is more difficult, and a fault on one line will take out at least two
- Double Bus Breaker: Now each line is fully protected when a breaker is out, so high reliability, but more costly







Fig D: Double Bus Double Breaker

# **Ring Bus, Breaker and Half**

- As the name implies with a ring bus the breakers form a ring; number of breakers is same as number of devices; any breaker can be removed for maintenance
- The breaker and half has two buses and uses three breakers for two devices; both breakers and buses can be removed for maintenance





Fig G: Breaker and Half

# **EMS and Planning Models**

- EMS Model
  - Used for real-time operations
  - Called full topology model
  - Has node-breaker detail

- Planning Model
  - Used for off-line analysis
  - Called consolidated model by PowerWorld
  - Has bus/branch detail





#### **Node-Breaker Consolidation**

- One approach to modeling systems with large numbers of ZBRs (zero branch reactances, such as from circuit breakers) is to just assume a small reactance and solve
  - This results in lots of buses and branches, resulting in a much larger problem
  - This can cause numerical problems in the solution
- The alterative is to consolidate the nodes that are connected by ZBRs into a smaller number of buses
  - After solution all nodes have the same voltage; use logic to determine the device flows

#### **Node-Breaker Example**



Case name is **FT\_11Node**. PowerWorld consolidates nodes (buses) into super buses; available in the Model Explorer: Solution, Details, Superbuses.

#### **Node-Breaker Example**



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Note there is ambiguity on how much power is flowing in each device in the ring bus (assuming each device really has essentially no impedance)

# **Contingency Analysis**

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- Contingency analysis is the process of checking the impact of statistically likely contingencies
  - Example contingencies include the loss of a generator, the loss of a transmission line or the loss of all transmission lines in a common corridor
  - Statistically likely contingencies can be quite involved, and might include automatic or operator actions, such as switching load
- Reliable power system operation requires that the system be able to operate with no unacceptable violations even when these contingencies occur
  - N-1 reliable operation considers the loss of any single element

# **Contingency Analysis**



- Of course this process can be automated with the usual approach of first defining a contingency set, and then sequentially applying the contingencies and checking for violations
  - This process can naturally be done in parallel
  - Contingency sets can get quite large, especially if one considers N-2 (outages of two elements) or N-1-1 (initial outage, followed by adjustment, then second outage
- The assumption is usually most contingencies will not cause problems, so screening methods can be used to quickly eliminate many contingencies
  - We'll cover these later

# **Contingency Analysis in PowerWorld**



#### • Automated using the Contingency Analysis tool

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# Power System Control and Sensitivities



- A major issue with power system operation is the limited capacity of the transmission system
  - lines/transformers have limits (usually thermal)
  - no direct way of controlling flow down a transmission line (e.g., there are no valves to close to limit flow)
  - open transmission system access associated with industry restructuring is stressing the system in new ways
- We need to indirectly control transmission line flow by changing the generator outputs
- Similar control issues with voltage

# **Indirect Transmission Line Control**



• What we would like to determine is how a change in generation at bus k affects the power flow on a line from bus i to bus j.



The assumption is that the change in generation is absorbed by the slack bus

#### **Power Flow Simulation - Before**



- One way to determine the impact of a generator change is to compare a before/after power flow.
- For example below is a three bus case with an overload



#### **Power Flow Simulation - After**

 Increasing the generation at bus 3 by 95 MW (and hence decreasing it at bus 1 by a corresponding amount), results in a 30.3 MW drop in the MW flow on the line from bus 1 to 2, and a 64.7 MW drop on the flow from 1 to 3.



Expressed as a percent, 30.3/95 =32% and 64.7/95=68%

## **Analytic Calculation of Sensitivities**

 Calculating control sensitivities by repeat power flow solutions is tedious and would require many power flow solutions. An alternative approach is to analytically calculate these values

The power flow from bus i to bus j is

$$P_{ij} \approx \frac{|V_i| |V_j|}{X_{ij}} \sin(\theta_i - \theta_j) \approx \frac{\theta_i - \theta_j}{X_{ij}}$$
  
So  $\Delta P_{ij} \approx \frac{\Delta \theta_i - \Delta \theta_j}{X_{ij}}$  We just need to get  $\frac{\Delta \theta_{ij}}{\Delta P_{Gk}}$ 

#### **Analytic Sensitivities**



From the fast decoupled power flow we know  $\Delta \mathbf{\theta} = \mathbf{B}^{-1} \Delta \mathbf{P}(\mathbf{x})$ 

So to get the change in  $\Delta \theta$  due to a change of generation at bus k, just set  $\Delta \mathbf{P}(\mathbf{x})$  equal to

all zeros except a minus one at position k.

$$\Delta \mathbf{P} = \begin{bmatrix} 0 \\ \vdots \\ -1 \\ 0 \\ \vdots \end{bmatrix} \leftarrow \text{Bus k}$$

#### **Three Bus Sensitivity Example**



For a three bus, three line case with  $Z_{\text{line}} = j0.1$ 

$$\mathbf{Y}_{\text{bus}} = j \begin{bmatrix} -20 & 10 & 10 \\ 10 & -20 & 10 \\ 10 & 10 & -20 \end{bmatrix} \rightarrow \mathbf{B} = \begin{bmatrix} -20 & 10 \\ 10 & -20 \end{bmatrix}$$

Hence for a change of generation at bus 3

$$\begin{bmatrix} \Delta \theta_2 \\ \Delta \theta_3 \end{bmatrix} = \begin{bmatrix} -20 & 10 \\ 10 & -20 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 0.0333 \\ 0.0667 \end{bmatrix}$$
  
Then  $\Delta P_{3 \text{ to } 1} = \frac{0.0667 - 0}{0.1} = 0.667 \text{ pu}$   
 $\Delta P_{3 \text{ to } 2} = 0.333 \text{ pu}$   $\Delta P_{2 \text{ to } 1} = 0.333 \text{ pu}$ 

#### More General Sensitivity Analysis: Notation



- Some authors designate the slack as bus zero; an alternative approach, that is easier to implement in cases with multiple islands and hence slacks, is to allow any bus to be the slack, and just set its associated equations to trivial equations just stating that the slack bus voltage is constant
- We may denote the  $k^{th}$  transmission line or transformer in the system,  $\mathbb{P}_k$ , as



# Notation, cont.



- We'll denote the real power flowing on □<sub>k</sub> from bus i to bus j as f<sub>k</sub>
- The vector of real power flows on the *L* lines is:

**f** @ 
$$[f_{\ell_1}, f_{\ell_2}, \cdots, f_{\ell_L}]^T$$

which we simplify to  $\mathbf{f} = [f_1, f_2, \cdots, f_L]^T$ 

• The bus real and reactive power injection vectors are

**p** @ 
$$[p^{1}, p^{2}, \dots, p^{N}]^{T}$$

**q** @ 
$$[q^{1}, q^{2}, \dots, q^{N}]^{T}$$

#### Notation, cont.



- The series admittance of line  $\mathbb{P}$  is  $g_{\mathbb{P}} + jb_{\mathbb{P}}$  and we define  $\tilde{\mathbf{B}} @ -diag\{b_1, b_2, \cdots, b_L\}$
- We define the L×N incidence matrix



The component j of  $\mathbf{a}_i$  is nonzero whenever line  $\mathbb{P}_i$  is coincident with node j. Hence **A** is quite sparse, with two nonzeros per row

#### Analysis Example: Available Transfer Capability

- The power system available transfer capability or ATC is defined as the maximum additional MW that can be transferred between two specific areas, while meeting all the specified pre- and post-contingency system conditions
- ATC impacts measurably the market outcomes and system reliability and, therefore, the ATC values impact the system and market behavior
- A useful reference on ATC is *Available Transfer Capability Definitions and Determination* from NERC, June 1996 (available online)

# ATC and Its Key Components



- Total transfer capability (TTC)
  - Amount of real power that can be transmitted across an interconnected transmission network in a reliable manner, including considering contingencies
- Transmission reliability margin (TRM)
  - Amount of TTC needed to deal with uncertainties in system conditions; typically expressed as a percent of TTC
- Capacity benefit margin (CBM)
  - Amount of TTC needed by load serving entities to ensure access to generation; typically expressed as a percent of TTC

# **ATC and Its Key Components**



- Uncommitted transfer capability (UTC) UTC P TTC – existing transmission commitment
- Formal definition of ATC is
   ATC I UTC CBM TRM
- We focus on determining  $U_{m,n}$ , the UTC from node m to node n
- $U_{m,n}$  is defined as the maximum additional MW that can be transferred from node m to node n without violating any limit in either the base case or in any postcontingency conditions

# **UTC (or TTC)** Evaluation



*s.t*.

$$f_{\ell}^{(j)} + \Delta f_{\ell} \leq f_{\ell}^{max} \quad \forall \ell \in L$$

for the base case j = 0 and each contingency case

$$i = 1, 2 \dots, J$$
 31

# **Conceptual Solution Algorithm**



- 2. Compute  $\Delta t^{(k+1)} = \Delta t^{(k)} + \delta$
- 3. Solve the power flow for the new  $\Delta t^{(k+1)}$
- 4. Check for limit violations: if violation is found set  $U_{m,n}^{j} = \Delta t^{(k)}$  and stop; else set k=k+1, and goto 2

# **Conceptual Solution Algorithm, cont.**

- This algorithm is applied for the base case (j=0) and each specified contingency case, j=1,2,...J
- The final UTC,  $U_{m,n}$  is then determined by

$$U_{m,n} = \min_{0 \le j \le J} \left\{ U_{m,n}^{(j)} \right\}$$

• This algorithm can be easily performed on parallel processors since each contingency evaluation is independent of the other

#### **Five Bus Example: Reference**



PowerWorld Case: **B5\_DistFact** 



#### **Five Bus Example: Reference**

					<b>n</b>
l	i	j	<b>g</b> _{\ell}	<b>b</b> <sub>ℓ</sub>	$f_{\ell}^{max}(MW)$
$\ell_1$	1	2	0	6.25	150
$\ell_2$	1	3	0	12.5	400
$\ell_3$	1	4	0	12.5	150
$\ell_4$	2	3	0	12.5	150
$\ell_5$	3	4	0	12.5	150
$\ell_6$	4	5	0	10	1,000

#### **Five Bus Example**



- We evaluate  $U_{2,3}$  using the previous procedure
  - Gradually increase generation at Bus 2 and load at Bus 3
- We consider the base case and the single contingency with line 2 outaged (between 1 and 3): J = 1
- Simulation results show for the base case that  $U_{2,3}^{(0)} = 45 MW$
- And for the contingency that  $U_{2,3}^{(1)} = 24 MW$
- Hence  $U_{2,3} = min\{U_{2,3}^{(0)}, U_{2,3}^{(1)}\} = 24 MW$

# Five Bus: Maximum Base Case Transfer



#### Five Bus: Maximum Contingency Transfer



# **Computational Considerations**



- Obviously such a brute force approach can run into computational issues with large systems
- Consider the following situation:
  - 10 iterations for each case
  - 6,000 contingencies
  - 2 seconds to solve each power flow
- It will take over 33 hours to compute a single UTC for the specified transfer direction from m to n.
- Consequently, there is an acute need to develop fast tools that can provide satisfactory estimates



• Denote the system state by

$$\mathbf{x} @ \begin{bmatrix} \boldsymbol{\theta} \\ \mathbf{V} \end{bmatrix} \qquad \begin{array}{l} \boldsymbol{\theta} @ [\boldsymbol{\theta}^{1}, \boldsymbol{\theta}^{2}, \cdots, \boldsymbol{\theta}^{N}]^{T} \\ \mathbf{V} @ [\boldsymbol{V}^{1}, \boldsymbol{V}^{2}, \cdots, \boldsymbol{V}^{N}]^{T} \end{array}$$

Denote the conditions corresponding to the existing commitment/dispatch by s<sup>(0)</sup>, p<sup>(0)</sup> and f<sup>(0)</sup> so that

$$\begin{cases} g(\mathbf{x}^{(\theta)}, \mathbf{p}^{(\theta)}) = \mathbf{0} & \text{the power flow equations} \\ \mathbf{f}^{(\theta)} = \mathbf{h}(\mathbf{x}^{(\theta)}) & \text{line real power flow vector} \end{cases}$$

$$\mathbf{g}(\mathbf{x},\mathbf{p}) = \begin{bmatrix} \mathbf{g}^{P}(\mathbf{x},\mathbf{p}) \\ \mathbf{g}^{Q}(\mathbf{x},\mathbf{p}) \end{bmatrix}$$

**g** includes the real and reactive power balance equations

$$g_{k}^{P}(\underline{s},\underline{p}) = V^{k} \sum_{m=1}^{N} \left( V^{m} \left[ G_{km} cos \left( \theta^{k} - \theta^{m} \right) + B_{km} sin \left( \theta^{k} - \theta^{m} \right) \right] \right) - p^{k}$$

$$g_{k}^{Q}(\underline{s},\underline{p}) = V^{m} \sum_{m=1}^{N} \left( V^{m} \left[ G_{km} sin \left( \theta^{k} - \theta^{m} \right) - B_{km} cos \left( \theta^{k} - \theta^{m} \right) \right] \right) - q^{k}$$

$$h_{\ell}(\underline{s}) = g_{\ell}\left[\left(V^{i}\right)^{2} - V^{i}V^{j}cos(\theta^{i} - \theta^{j})\right] - b_{\ell}V^{i}V^{j}sin(\theta^{i} - \theta^{j}), \ \ell = (i,j)$$





- For a small change,  $\Delta \mathbf{p}$ , that moves the injection from  $\mathbf{p}^{(0)}$  to  $\mathbf{p}^{(0)} + \Delta \mathbf{p}$ , we have a corresponding change in the state  $\Delta \mathbf{x}$  with  $\mathbf{g} (\mathbf{x}^{(0)} + \Delta \mathbf{x}, p^{(0)} + \Delta \mathbf{p}) = \mathbf{0}$
- We then apply a first order Taylor's series expansion  $g(x^{(\theta)} + \Delta x, p^{(\theta)} + \Delta p) = g(x^{(\theta)}, p^{(\theta)}) + \frac{\partial g}{\partial x}\Big|_{(x^{(\theta)}p^{(\theta)})} \Delta x$

+ 
$$\frac{\partial \mathbf{g}}{\partial \mathbf{p}}\Big|_{\left(\mathbf{x}^{(\theta)}\mathbf{p}^{(\theta)}\right)}\Delta \mathbf{p} + h.o.t.$$



- We consider this to be a "small signal" change, so we can neglect the higher order terms (h.o.t.) in the expansion
- Hence we should still be satisfying the power balance equations with this perturbation; so

$$\frac{\partial \mathbf{g}}{\partial \mathbf{x}}\Big|_{\left(\mathbf{x}^{(\theta)}\mathbf{p}^{(\theta)}\right)}\Delta \mathbf{x} + \frac{\partial \mathbf{g}}{\partial \mathbf{p}}\Big|_{\left(\mathbf{x}^{(\theta)}\mathbf{p}^{(\theta)}\right)}\Delta \mathbf{p} \approx \mathbf{0}$$



• Also, from the power flow equations, we obtain



and then just the power flow Jacobian

$$\frac{\partial \mathbf{g}}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial \mathbf{g}^{P}}{\partial \mathbf{\theta}} & \frac{\partial \mathbf{g}^{P}}{\partial \mathbf{V}} \\ \frac{\partial \mathbf{g}^{Q}}{\partial \mathbf{\theta}} & \frac{\partial \mathbf{g}^{Q}}{\partial \mathbf{V}} \end{bmatrix} = \mathbf{J}(\mathbf{x}, \mathbf{p})$$



• With the standard assumption that the power flow Jacobian is nonsingular, then

$$\Delta \mathbf{x} \approx \left[ \mathbf{J}(\mathbf{x}^{(0)},\mathbf{p}^{(0)}) \right]^{-1} \begin{bmatrix} \mathbf{I} \\ \mathbf{0} \end{bmatrix} \Delta \mathbf{p}$$

• We can then compute the change in the line real power flow vector

$$\Delta \mathbf{f} \approx \left[\frac{\partial \mathbf{h}}{\partial \mathbf{x}}\right]^T \Delta \mathbf{s} \approx \left[\frac{\partial \mathbf{h}}{\partial \mathbf{x}}\right]^T \left[J(\mathbf{x}^{(\theta)}, \mathbf{p}^{(\theta)})\right]^{-1} \begin{bmatrix} \mathbf{I} \\ \mathbf{0} \end{bmatrix} \Delta \mathbf{p}$$

# **Sensitivity Comments**



- Sensitivities can easily be calculated even for large systems
  - If  $\Delta \mathbf{p}$  is sparse (just a few injections) then we can use a fast forward; if sensitivities on a subset of lines are desired we could also use a fast backward
- Sensitivities are dependent upon the operating point
  - They also include the impact of marginal losses
- Sensitivities could easily be expanded to include additional variables in x (such as phase shifter angle), or additional equations, such as reactive power flow

# Sensitivity Comments, cont.

- Sensitivities are used in the optimal power flow; in that context a common application is to determine the sensitivities of an overloaded line to injections at all the buses
- In the below equation, how could we quickly get these values?

$$\Delta \mathbf{f} \approx \left[\frac{\partial \mathbf{h}}{\partial \mathbf{x}}\right]^T \Delta f \approx \left[\frac{\partial \mathbf{h}}{\partial x}\right]^T \left[J\left(\mathbf{x}^{(\theta)}, \mathbf{p}^{(\theta)}\right)\right]^{-1} \begin{bmatrix}\mathbf{I}\\\mathbf{0}\end{bmatrix} \Delta \mathbf{p}$$

 A useful reference is O. Alsac, J. Bright, M. Prais, B. Stott, "Further Developments in LP-Based Optimal Power Flow," IEEE. Trans. on Power Systems, August 1990, pp. 697-711; especially see equation 3.

# Sensitivity Example in PowerWorld



- Open case **B5\_DistFact** and then Select **Tools**, **Sensitivities, Flow and Voltage Sensitivities** 
  - Select Single Meter, Multiple Transfers, Buses page
  - Select the Device Type (Line/XFMR), Flow Type (MW), then select the line (from Bus 2 to Bus 3)
  - Click Calculate Sensitivities; this shows impact of a single injection going to the slack bus (Bus 1)
  - For our example of a transfer from 2 to 3 the value is the result we get for bus 2 (0.5440) minus the result for bus 3 (-0.1808) = 0.7248
  - With a flow of 118 MW, we would hit the 150 MW limit with (150-118)/0.7248 =44.1MW, close to the limit we found of 45MW

# Sensitivity Example in PowerWorld



- If we change the conditions to the anticipated maximum loading (changing the load at 2 from 118 to 118+44=162 MW) and we re-evaluate the sensitivity we note it has changed little (from -0.7248 to -0.7241)
  - Hence a linear approximation (at least for this scenario) could be justified
- With what we know so far, to handle the contingency situation, we would have to simulate the contingency, and reevaluate the sensitivity values
  - We'll be developing a quicker (but more approximate) approach next