ECEN 460 Power System Operation and Control Spring 2025

Lecture 3: Complex Power, Three-Phase

Prof. Tom Overbye Dept. of Electrical and Computer Engineering Texas A&M University overbye@tamu.edu



Transformer Fire Video





After class the video will be available in Canvas

Complex Power

Power

$$p(t) = v(t) i(t)$$

$$v(t) = V_{\max} \cos(\omega t + \theta_V)$$

$$i(t) = I_{\max} \cos(\omega t + \theta_I)$$

$$\cos \alpha \cos \beta = \frac{1}{2} [\cos(\alpha - \beta) + \cos(\alpha + \beta)]$$

$$p(t) = \frac{1}{2} V_{\max} I_{\max} [\cos(\theta_V - \theta_I) + \cos(2\omega t + \theta_V + \theta_I)]$$



Complex Power, cont'd

Average Power

$$p(t) = \frac{1}{2} V_{\max} I_{\max} [\cos(\theta_V - \theta_I) + \cos(2\omega t + \theta_V + \theta_I)]$$

$$P_{avg} = \frac{1}{T} \int_0^T p(t) dt$$

$$= \frac{1}{2} V_{\max} I_{\max} \cos(\theta_V - \theta_I)$$

$$= |V| |I| \cos(\theta_V - \theta_I)$$

Power Factor Angle = $\phi = \theta_V - \theta_I$

Complex Power



$$S = |V||I|[\cos(\theta_V - \theta_I) + j\sin(\theta_V - \theta_I)]$$

= P + jQ $= V I^*$

(Note: S is a complex number but not a phasor)

- P = Real Power (W, kW, MW)
- Q = Reactive Power (var, kvar, Mvar)
- S = Complex power (VA, kVA, MVA)

Power Factor (pf) = $\cos\phi$

If current leads voltage then pf is leading

If current lags voltage then pf is lagging

Relationships between real, reactive and complex power

$$P = |S| \cos \phi$$
$$Q = |S| \sin \phi = \pm |S| \sqrt{1 - pf^2}$$

Example: A load draws 100 kW with a leading pf of 0.85. What are ϕ (power factor angle), Q and |S|?

$$\phi = -\cos^{-1} 0.85 = -31.8^{\circ}$$
$$|S| = \frac{100kW}{0.85} = 117.6 \text{ kVA}$$
$$Q = 117.6\sin(-31.8^{\circ}) = -62.0 \text{ kVar}$$



Conservation of Power

A M

- At every node (bus) in the system
 - Sum of real power into node must equal zero
 - Sum of reactive power into node must equal zero
- This is a direct consequence of Kirchhoff's current law, which states that the total current into each node must equal zero.
 - Conservation of power follows since $S = VI^*$

Conversation of Power Example

Earlier we found $I = 20 \angle -6.9^{\circ}$ amps

 $S = V I^* = 100 \angle 30^\circ \times 20 \angle 6.9^\circ = 2000 \angle 36.9^\circ$ VA $\phi = 36.9^{\circ}$ pf = 0.8 lagging $S_{R} = V_{R} I^{*} = 4 \times 20 \angle -6.9^{\circ} \times 20 \angle 6.9^{\circ}$ $P_{R} = 1600W = |I|^{2} R \quad (Q_{R} = 0)$ $S_{L} = V_{L} I^{*} = 3j \times 20 \angle -6.9^{\circ} \times 20 \angle 6.9^{\circ}$ $Q_{\rm L} = 1200 \, {\rm var} = |I|^2 X \quad (P_{\rm L} = 0)$



Power Consumption in Devices

Resistors only consume real power

$$P_{\text{Resistor}} = \left| I_{\text{Resistor}} \right|^2 R$$

Inductors only consume reactive power

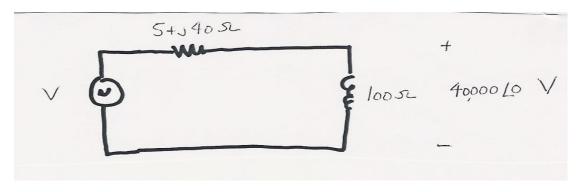
$$Q_{\text{Inductor}} = \left| I_{\text{Inductor}} \right|^2 X_{\text{L}}$$

Capacitors only generate reactive power

$$Q_{\text{Capacitor}} = -\left|I_{\text{Capacitor}}\right|^2 X_{\text{C}} \qquad X_{C} = \frac{1}{\omega C}$$
$$Q_{\text{Capacitor}} = -\frac{\left|V_{\text{Capacitor}}\right|^2}{X_{\text{C}}} \text{ (Note-some define } X_{\text{C}} \text{ negative)}$$



Example



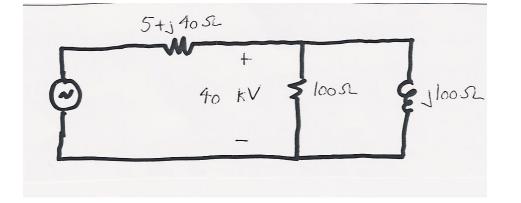
A M

First solve the basic circuit

- $I = \frac{40000 \angle 0^{\circ} V}{100 \angle 0^{\circ} \Omega} = 400 \angle 0^{\circ} \text{ Amps}$
- $V = 40000 \angle 0^{\circ} + (5 + j40) \ 400 \angle 0^{\circ}$
 - $= 42000 + j16000 = 44.9 \angle 20.8^{\circ} \text{ kV}$
- $S = VI^* = 44.9k \angle 20.8^\circ \times 400 \angle 0^\circ$
 - $= 17.98 \angle 20.8^{\circ} \text{ MVA} = 16.8 + j6.4 \text{ MVA}$

Example, cont'd





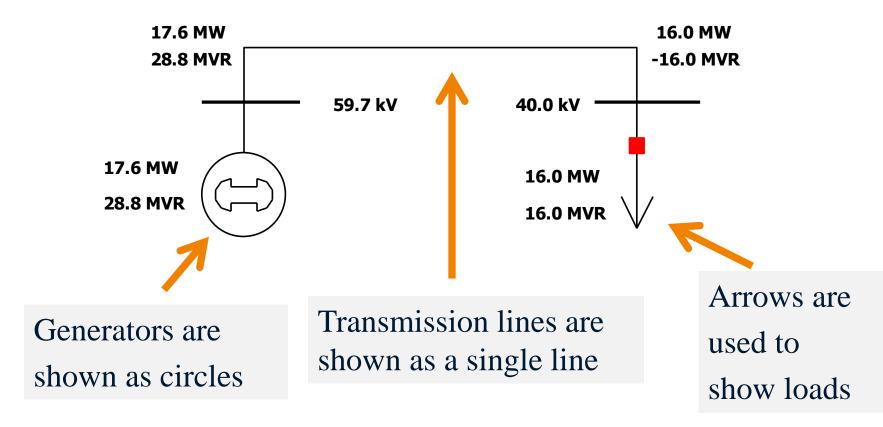
Now add additional reactive power load and resolve

$$Z_{Load} = 70.7 \angle 45^{\circ} \quad pf = 0.7 \text{ lagging}$$
$$I = 564 \angle -45^{\circ} \text{ Amps}$$
$$V = 59.7 \angle 13.6^{\circ} \text{ kV}$$

 $S = 33.7 \angle 58.6^{\circ} MVA = 17.6 + j28.8 MVA$

Power System Notation

• Power system components are usually shown as oneline diagrams Previous circuit redrawn

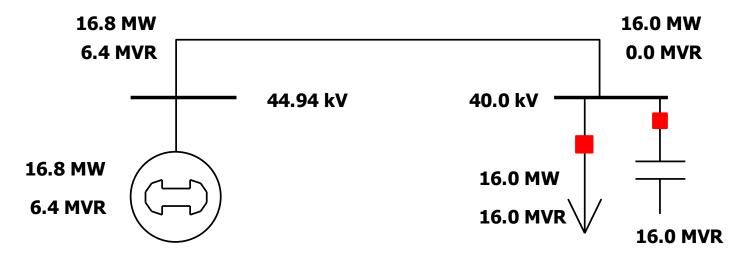


11

ĀM

Reactive Compensation

• Key idea of reactive compensation is to supply reactive power locally. In the previous example this can be done by adding a 16 Mvar capacitor at the load



Power engineers think of capacitors in terms of how much reactive power they can supply at a specified (rated) voltage; not in terms of Farads

Compensated circuit is identical to first example with just real power load

Reactive Compensation, cont'd

- Reactive compensation decreased the line flow from 564 Amps to 400 Amps. This has advantages
 - Lines losses, which are equal to $I^2 R$ decrease
 - Lower current allows utility to use small wires, or alternatively, supply more load over the same wires
 - Voltage drop on the line is less
- Reactive compensation is used extensively by utilities
- Capacitors can be used to "correct" a load's power factor to an arbitrary value.

Power Factor Correction Example

Assume we have 100 kVA load with pf=0.8 lagging, and would like to correct the pf to 0.95 lagging

$$S = 80 + j60 \text{ kVA} \qquad \phi = \cos^{-1} 0.8 = 36.9^{\circ}$$
PF of 0.95 requires $\phi_{\text{desired}} = \cos^{-1} 0.95 = 18.2^{\circ}$

$$S_{\text{new}} = 80 + j(60 - Q_{\text{cap}})$$

$$\frac{60 - Q_{\text{cap}}}{80} = \tan 18.2^{\circ} \implies 60 - Q_{\text{cap}} = 26.3 \text{ kvar}$$

$$Q_{\text{cap}} = 33.7 \text{ kvar}$$

Distribution System Capacitors

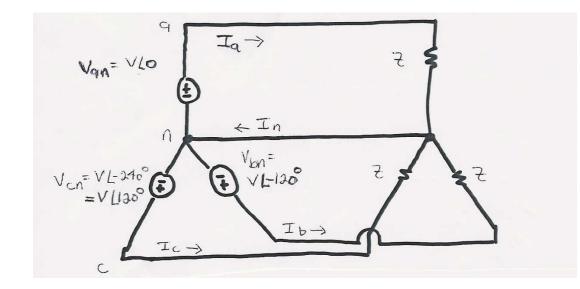




A M

- A balanced three-phase (ϕ) system has
 - three voltage sources with equal magnitude, but with an angle shift of 120°
 - equal loads on each phase
 - equal impedance on the lines connecting the generators to the loads
- Bulk power systems are almost exclusively 3\$
- Single-phase is used primarily only in low voltage, low power settings, such as residential and some commercial

Balanced Three-Phase: No Neutral Current



$$I_{n} = I_{a} + I_{b} + I_{c}$$

$$I_{n} = \frac{V}{Z} (1 \angle 0^{\circ} + 1 \angle -120^{\circ} + 1 \angle 120^{\circ}) = 0$$

$$S = V_{an} I_{an}^{*} + V_{bn} I_{bn}^{*} + V_{cn} I_{cn}^{*} = 3 V_{an} I_{an}^{*}$$

Advantages of Three-Phase Power

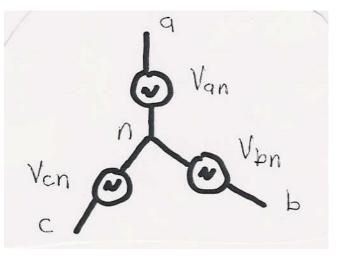
- Can transmit more power for same amount of wire (twice as much as single phase)
- Torque produced by three-phase machines is constant
- Three-phase machines use less material for same power rating
- Three-phase machines start more easily than single-phase machines

Three-Phase Wye Connection

AM

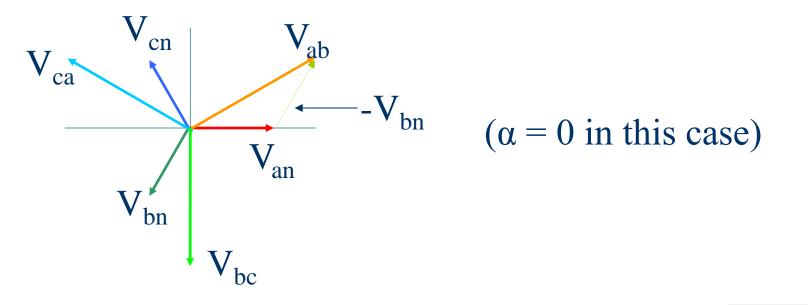
- There are two ways to connect three-phase systems
 - Wye (Y)
 - Delta (Δ)
 - Wye Connection Voltages

$$V_{an} = |V| \angle \alpha^{\circ}$$
$$V_{bn} = |V| \angle \alpha^{\circ} - 120^{\circ}$$
$$V_{cn} = |V| \angle \alpha^{\circ} + 120^{\circ}$$



Wye Connection Line Voltages





$$V_{ab} = V_{an} - V_{bn} = |V| (1 \angle \alpha - 1 \angle \alpha + 120^{\circ})$$
$$= \sqrt{3} |V| \angle \alpha + 30^{\circ}$$
$$V_{bc} = \sqrt{3} |V| \angle \alpha - 90^{\circ}$$
$$V_{ca} = \sqrt{3} |V| \angle \alpha + 150^{\circ}$$

The line to line voltages are also balanced

Wye Connection, cont'd

• Define voltage/current across/through device to be phase voltage/current

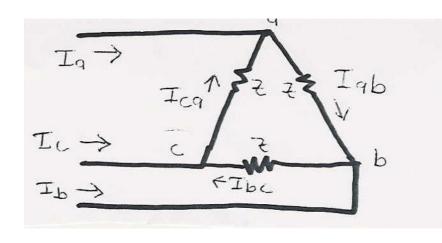
•

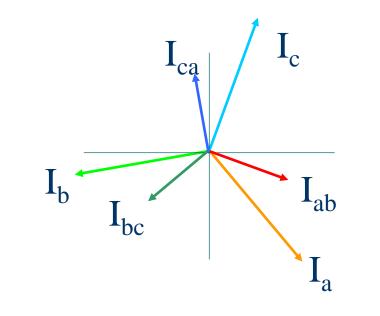
• Define voltage/current across/through lines to be line voltage/current

$$V_{Line} = \sqrt{3} V_{Phase} \ 1 \angle 30^{\circ} = \sqrt{3} V_{Phase} \ e^{\frac{j\pi}{6}}$$
$$I_{Line} = I_{Phase}$$
$$S_{3\phi} = 3 V_{Phase} \ I_{Phase}^{*}$$

A M

Delta Connection





ÄM

For the Delta phase voltages equal line voltages

For currents

$$I_{a} = I_{ab} - I_{ca}$$

= $\sqrt{3}I_{ab} \angle -30^{\circ}$
$$I_{b} = I_{bc} - I_{ab}$$

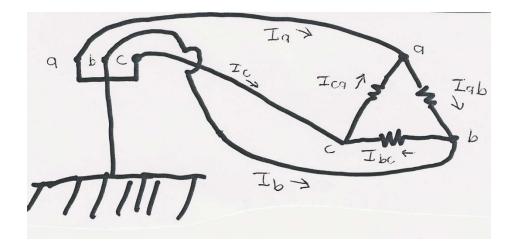
$$I_{c} = I_{ca} - I_{bc}$$

$$S_{3\phi} = 3V_{Phase} I_{Phase}^{*}$$

Three-Phase Example



Assume a Δ -connected load is supplied from a 3 ϕ 13.8 kV (L-L) source with Z = 100 $\angle 20^{\circ}\Omega$



 $V_{ab} = 13.8 \angle 0^{\circ} kV$ $V_{bc} = 13.8 \angle -120^{\circ} kV$ $V_{ca} = 13.8 \angle 120^{\circ} kV$

 $I_{ab} = \frac{13.8 \angle 0^{\circ} \, kV}{100 \angle 20^{\circ} \, \Omega} = 138 \angle -20^{\circ} \, amps$

 $I_{bc} = 138 \angle -140^{\circ} amps$ $I_{ca} = 138 \angle 100^{\circ} amps$

Three-Phase Example, cont'd

$$I_a = I_{ab} - I_{ca} = 138 \angle -20^\circ - 138 \angle 100^\circ$$

= 239 \arrow -50^\circ amps

$$I_b = 239 \angle -170^\circ \text{ amps } I_c = 239 \angle 70^\circ \text{ amps}$$

$$S = 3 \times V_{ab} I_{ab}^* = 3 \times 13.8 \angle 0^\circ kV \times 138 \angle 20^\circ amps$$

$$= 5.7 \angle 20^{\circ} \text{ MVA}$$

- = 5.37 + j1.95 MVA
- pf = $\cos 20^\circ = 0.94$ lagging

A M

Delta-Wye Transformation



To simplify analysis of balanced 3ϕ systems:

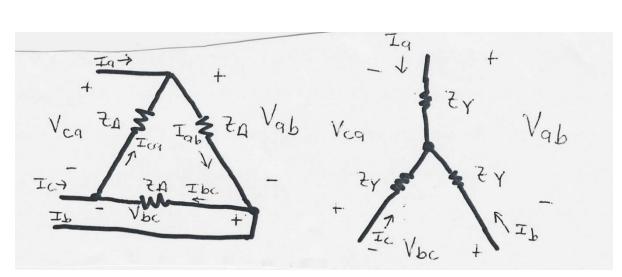
- 1) Δ -connected loads can be replaced by Y-connected loads with $Z_Y = \frac{1}{3}Z_{\Delta}$
- 2) Δ -connected sources can be replaced by Y-connected sources with $V_{\text{phase}} = \frac{V_{Line}}{\sqrt{3}/30^{\circ}}$

Delta-Wye Transformation Proof

From the Δ side we get

$$I_{a} = \frac{V_{ab}}{Z_{\Delta}} - \frac{V_{ca}}{Z_{\Delta}} = \frac{V_{ab} - V_{ca}}{Z_{\Delta}}$$

Hence $Z_{\Delta} = \frac{V_{ab} - V_{ca}}{I_{a}}$



From the *Y* side we get

$$V_{ab} = Z_Y(I_a - I_b) \qquad V_{ca} = Z_Y(I_c - I_a)$$
$$V_{ab} - V_{ca} = Z_Y(2I_a - I_b - I_c)$$
Since
$$I_a + I_b + I_c = 0 \Longrightarrow I_a = -I_b - I_c$$

Hence
$$V_{ab} - V_{ca} = 3 Z_Y I_a$$

$$3 Z_Y = \frac{V_{ab} - V_{ca}}{I_a} = Z_\Delta$$

Therefore

 $Z_Y = \frac{1}{3}Z_\Delta$

ĀМ

Three-Phase Transmission Line



Transmission Arcing Video



Modeling Cautions

- AM
- "All models are wrong but some are useful," George Box, *Empirical Model-Building and Response Surfaces*, (1987, p. 424)
 - Models are an approximation to reality, not reality, so they always have some degree of approximation
 - Box went on to say that the practical question is how wrong to they have to be to not be useful
- A good part of engineering is deciding what is the appropriate level of modeling, and knowing under what conditions the model will fail
- Of course engineering often involves using widely accepted modeling and analysis approaches for common problems. Increasingly this requires adhering to particular standards
 - Still, the engineer needs to know the conditions under which these approaches fail!

Per Phase Analysis

- Per phase analysis allows analysis of balanced three-phase systems with the same effort as for a single-phase system
- Balanced Three-Phase Theorem: For a balanced three-phase system with
 - All loads and sources Y connected
 - No mutual Inductance between phases
- Then
 - All neutrals are at the same potential
 - All phases are COMPLETELY decoupled
 - All system values are the same sequence as sources. The sequence order we've been using (phase b lags phase a and phase c lags phase a) is known as "positive" sequence (negative and zero sequence systems are mostly covered in ECEN 459)

Per Phase Analysis Procedure

To do per phase analysis

- 1. Convert all Δ load/sources to equivalent Y's
- 2. Solve phase "a" independent of the other phases
- 3. Total system power $S = 3 V_a I_a^*$
- 4. If desired, phase "b" and "c" values can be determined by inspection (i.e., $\pm 120^{\circ}$ degree phase shifts)
- 5. If necessary, go back to original circuit to determine line-line values or internal Δ values.



Per Phase Example

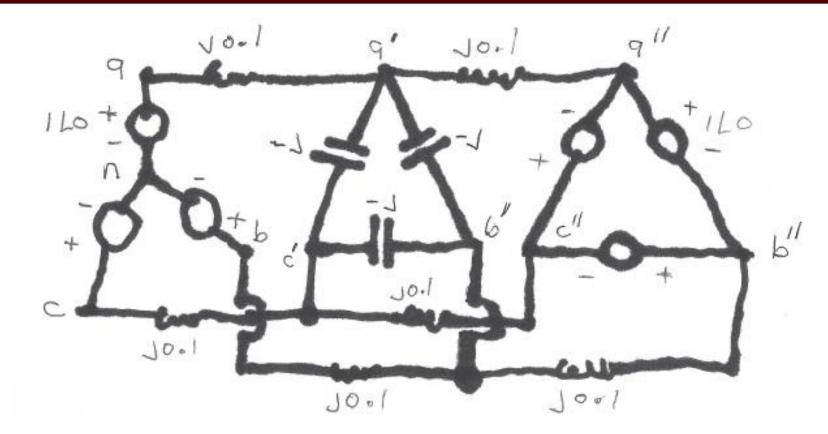


Assume a three-phase, Y-connected generator with $V_{an} = 1 \angle 0^{\circ}$ volts supplies a Δ -connected load with $Z_{\Delta} = -j\Omega$ through a transmission line with impedance of j0.1 Ω per phase. The load is also connected to a Δ -connected generator with $V_{a"b"} = 1 \angle 0^{\circ}$ through a second transmission line which also has an impedance of j0.1 Ω per phase.

Find

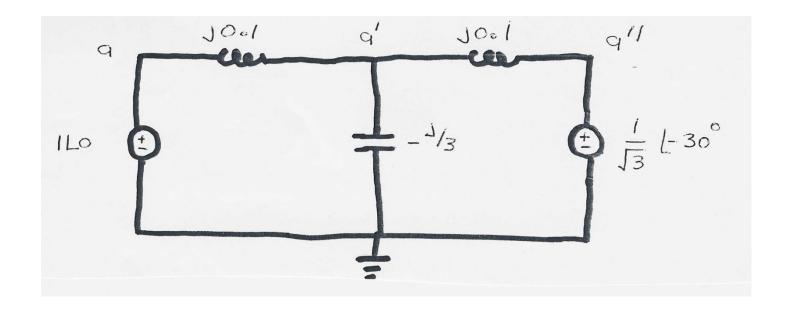
- 1. The load voltage $V_{a'b'}$
- 2. The total power supplied by each generator, $S_{\rm Y}$ and S_{Δ}

Per Phase Example, cont'd



First convert the delta load and source to equivalent Y values and draw just the "a" phase circuit A M

Per Phase Example, cont'd



To solve the circuit, write the KCL equation at a' $(V_a^{'} - 1 \angle 0)(-10j) + V_a^{'}(3j) + (V_a^{'} - \frac{1}{\sqrt{3}} \angle -30^\circ)(-10j) = 0$



Per Phase Example, cont'd

To solve the circuit, write the KCL equation at a'

$$(V_{a}' - 1 \angle 0)(-10j) + V_{a}'(3j) + (V_{a}' - \frac{1}{\sqrt{3}} \angle -30^{\circ})(-10j) = 0$$

$$(10j + \frac{10}{\sqrt{3}} \angle 60^{\circ}) = V_{a}'(10j - 3j + 10j)$$

$$V_{a}' = 0.9 \angle -10.9^{\circ} \text{ volts} \qquad V_{b}' = 0.9 \angle -130.9^{\circ} \text{ volts}$$

$$V_{c}' = 0.9 \angle 109.1^{\circ} \text{ volts} \qquad V_{ab}' = 1.56 \angle 19.1^{\circ} \text{ volts}$$

$$S_{ygen} = 3V_{a}I_{a}^{*} = 3V_{a}\left(\frac{V_{a} - V_{a}'}{j0.1}\right)^{*} = 5.1 + j3.5 \text{ VA}$$

$$S_{\Delta gen} = 3V_a^{"} \left(\frac{V_a^{"} - V_a^{'}}{j0.1}\right)^{"} = -5.1 - j4.7 \text{ VA}$$



Power System Operations Overview

A M

- Goal is to provide an intuitive feel for power system operation
- Emphasis will be on the impact of the transmission system
- Introduce basic power flow concepts through small system examples

PowerWorld Simulator

- Commercial tool in actual use by utilities and others (1000+ customers in 70 countries)
- Originally designed to be well-suited to teaching students about power systems.
 Still has that capability while being full-featured for industry use
- Strengths are user-friendliness and advanced data visualization



• The computers here have the full (unlimited bus) version. There is a free student 42-bus version available at powerworld.com/gloveroverbyesarma

Per Unit



- A key problem in analyzing power systems is the large number of transformers.
 - It would be very difficult to continually have to refer transformer values (like their impedances) to the different sides of the transformers
- This problem is avoided by a normalization of all variables.
- This normalization is known as per unit analysis

quantity in per unit = $\frac{\text{actual quantity}}{\text{base value of quantity}}$

• Engineers commonly talk about voltages in per unit. A 138 kV (base) transmission line operating at 140 kV is 140/138 = 1.022 p.u.